

# Assembly and Operating Manual

## GSP-P

### 2-Finger-parallel gripper



## Imprint

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thank you for trusting our products and our family-owned company, the leading technology supplier of robots and production machines.

Our team is always available to answer any questions on this product and other solutions. Ask us questions and challenge us. We will find a solution!

Best regards,

Your SCHUNK team

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# 1 General

## 1.1 About this manual

This manual contains important information for a safe and appropriate use of the product.

This manual is an integral part of the product and must be kept accessible for the personnel at all times.

Before starting work, the personnel must have read and understood this operating manual. Prerequisite for safe working is the observance of all safety instructions in this manual.

Illustrations in this manual are provided for basic understanding and may differ from the actual product design.

In addition to these instructions, the documents listed under [Applicable documents](#) [► 6] are applicable.

### 1.1.1 Presentation of Warning Labels

To make risks clear, the following signal words and symbols are used for safety notes.



#### **⚠ DANGER**

##### **Danger for persons!**

Non-observance will inevitably cause irreversible injury or death.



#### **⚠ WARNING**

##### **Dangers for persons!**

Non-observance can lead to irreversible injury and even death.



#### **⚠ CAUTION**

##### **Dangers for persons!**

Non-observance can cause minor injuries.

#### **NOTICE**

##### **Material damage!**

Information about avoiding material damage.

### **1.1.2 Applicable documents**

- General terms of business\*
- Catalog data sheet of the purchased product \*
- Assembly and operating manuals of the accessories \*

The documents marked with an asterisk (\*) can be downloaded on our homepage **schunk.com**

### **1.1.3 Variants**

This operating manual applies to the following variations:

- GSP-P without gripping force maintenance
- GSP-P with gripping force maintenance "O.D. gripping" (AS or NC)
- GSP-P with gripping force maintenance "I.D. gripping" (IS or NO)

## **1.2 Warranty**

If the product is used as intended, the warranty is valid for 24 months from the ex-works delivery date under the following conditions:

- Observe the specified maintenance and lubrication intervals
- Observe the ambient conditions and operating conditions

Parts touching the workpiece and wear parts are not included in the warranty.

## **1.3 Scope of delivery**

The scope of delivery includes

- 2-Finger-parallel gripper GSP-P in the version ordered
- Assembly and Operating Manual
- Accessory pack

## **1.4 Accessories**

A wide range of accessories are available for this product

For information regarding which accessory articles can be used with the corresponding product variants, see catalog data sheet.

## 2 Basic safety notes

### 2.1 Intended use

The product is designed exclusively for gripping and temporarily holding workpieces or objects.

- The product may only be used within the scope of its technical data, [Technical data](#) [▶ 14].
- When implementing and operating components in safety-related parts of the control systems, the basic safety principles in accordance with DIN EN ISO 13849-2 apply. The proven safety principles in accordance with DIN EN ISO 13849-2 also apply to categories 1, 2, 3 and 4.
- The product is intended for installation in a machine/system. The applicable guidelines must be observed and complied with.
- The product is intended for industrial and industry-oriented use.
- Appropriate use of the product includes compliance with all instructions in this manual.

### 2.2 Not intended use

It is not intended use if the product is used, for example, as a pressing tool, stamping tool, lifting gear, guide for tools, cutting tool, clamping device or a drilling tool.

- Any utilization that exceeds or differs from the appropriate use is regarded as misuse.

### 2.3 Constructional changes

#### Implementation of structural changes

By conversions, changes, and reworking, e.g. additional threads, holes, or safety devices can impair the functioning or safety of the product or damage it.

- Structural changes should only be made with the written approval of SCHUNK.

### 2.4 Spare parts

#### Use of unauthorized spare parts

Using unauthorized spare parts can endanger personnel and damage the product or cause it to malfunction.

- Use only original spare parts or spares authorized by SCHUNK.

## 2.5 Gripper fingers

### Requirements for the gripper fingers

Stored energy within the product creates the risk of serious injuries and significant property damage.

- Arrange the gripper fingers in a way that the product reaches either the position "open" or "closed" in a de-energized state.
- Only exchange the gripper fingers when no residual energy remains in the product.
- Make sure that the product and the top jaws are a sufficient size for the application.

## 2.6 Ambient conditions and operating conditions

### Required ambient conditions and operating conditions

Incorrect ambient and operating conditions can make the product unsafe, leading to the risk of serious injuries, considerable material damage and/or a significant reduction to the product's life span.

- Make sure that the product is used only in the context of its defined application parameters, [Technical data](#) [► 14].

## 2.7 Personnel qualification

### Inadequate qualifications of the personnel

If the personnel working with the product is not sufficiently qualified, the result may be serious injuries and significant property damage.

- All work may only be performed by qualified personnel.
- Before working with the product, the personnel must have read and understood the complete assembly and operating manual.
- Observe the national safety regulations and rules and general safety instructions.

The following personal qualifications are necessary for the various activities related to the product:

#### Trained electrician

Due to their technical training, knowledge and experience, trained electricians are able to work on electrical systems, recognize and avoid possible dangers and know the relevant standards and regulations.

#### Qualified personnel

Due to its technical training, knowledge and experience, qualified personnel is able to perform the delegated tasks, recognize and avoid possible dangers and knows the relevant standards and regulations.

#### Instructed person

Instructed persons were instructed by the operator about the delegated tasks and possible dangers due to improper behaviour.

#### Service personnel of the manufacturer

Due to its technical training, knowledge and experience, service personnel of the manufacturer is able to perform the delegated tasks and to recognize and avoid possible dangers.



## 2.8 Personal protective equipment

### Use of personal protective equipment

Personal protective equipment serves to protect staff against danger which may interfere with their health or safety at work.

- When working on and with the product, observe the occupational health and safety regulations and wear the required personal protective equipment.
- Observe the valid safety and accident prevention regulations.
- Wear protective gloves to guard against sharp edges and corners or rough surfaces.
- Wear heat-resistant protective gloves when handling hot surfaces.
- Wear protective gloves and safety goggles when handling hazardous substances.
- Wear close-fitting protective clothing and also wear long hair in a hairnet when dealing with moving components.

## 2.9 Notes on safe operation

### Incorrect handling of the personnel

Incorrect handling and assembly may impair the product's safety and cause serious injuries and considerable material damage.

- Avoid any manner of working that may interfere with the function and operational safety of the product.
- Use the product as intended.
- Observe the safety notes and assembly instructions.
- Do not expose the product to any corrosive media. This does not apply to products that are designed for special environments.
- Eliminate any malfunction immediately.
- Observe the care and maintenance instructions.
- Observe the current safety, accident prevention and environmental protection regulations regarding the product's application field.

## 2.10 Transport

### Handling during transport

Incorrect handling during transport may impair the product's safety and cause serious injuries and considerable material damage.

- When handling heavy weights, use lifting equipment to lift the product and transport it by appropriate means.
- Secure the product against falling during transportation and handling.
- Stand clear of suspended loads.

## 2.11 Malfunctions

### Behavior in case of malfunctions

- Immediately remove the product from operation and report the malfunction to the responsible departments/persons.
- Order appropriately trained personnel to rectify the malfunction.
- Do not recommission the product until the malfunction has been rectified.
- Test the product after a malfunction to establish whether it still functions properly and no increased risks have arisen.

## 2.12 Disposal

### Handling of disposal

The incorrect handling of disposal may impair the product's safety and cause serious injuries as well as considerable material and environmental harm.

- Follow local regulations on dispatching product components for recycling or proper disposal.

## 2.13 Fundamental dangers

### General

- Observe safety distances.
- Never deactivate safety devices.
- Before commissioning the product, take appropriate protective measures to secure the danger zone.
- Disconnect power sources before installation, modification, maintenance, or calibration. Ensure that no residual energy remains in the system.
- If the energy supply is connected, do not move any parts by hand.
- Do not reach into the open mechanism or movement area of the product during operation.

### 2.13.1 Protection during handling and assembly

#### **Incorrect handling and assembly**

Incorrect handling and assembly may impair the product's safety and cause serious injuries and considerable material damage.

- Have all work carried out by appropriately qualified personnel.
- For all work, secure the product against accidental operation.
- Observe the relevant accident prevention rules.
- Use suitable assembly and transport equipment and take precautions to prevent jamming and crushing.

#### **Incorrect lifting of loads**

Falling loads may cause serious injuries and even death.

- Stand clear of suspended loads and do not step into their swiveling range.
- Never move loads without supervision.
- Do not leave suspended loads unattended.

### 2.13.2 Protection during commissioning and operation

#### **Falling or violently ejected components**

Falling and violently ejected components can cause serious injuries and even death.

- Take appropriate protective measures to secure the danger zone.
- Never step into the danger zone during operation.

### 2.13.3 Protection against dangerous movements

#### Unexpected movements

Residual energy in the system may cause serious injuries while working with the product.

- Switch off the energy supply, ensure that no residual energy remains and secure against inadvertent reactivation.
- Never rely solely on the response of the monitoring function to avert danger. Until the installed monitors become effective, it must be assumed that the drive movement is faulty, with its action being dependent on the control unit and the current operating condition of the drive. Perform maintenance work, modifications, and attachments outside the danger zone defined by the movement range.
- To avoid accidents and/or material damage, human access to the movement range of the machine must be restricted. Limit/prevent accidental access for people in this area due through technical safety measures. The protective cover and protective fence must be rigid enough to withstand the maximum possible movement energy. EMERGENCY STOP switches must be easily and quickly accessible. Before starting up the machine or automated system, check that the EMERGENCY STOP system is working. Prevent operation of the machine if this protective equipment does not function correctly.

### 2.13.4 Protection against electric shock

#### Possible electrostatic energy

Components or assembly groups may become electrostatically charged. When the electrostatic charge is touched, the discharge may trigger a shock reaction leading to injuries.

- The operator must ensure that all components and assembly groups are included in the local potential equalisation in accordance with the applicable regulations.
- While paying attention to the actual conditions of the working environment, the potential equalisation must be implemented by a specialist electrician according to the applicable regulations.
- The effectiveness of the potential equalisation must be verified by executing regular safety measurements.

## 2.14 Notes on particular risks



### **⚠ WARNING**

#### **Risk of injury from crushing and impacts!**

Serious injury could occur during the base jaw procedure and when breaking or loosening the gripper fingers.

- Wear suitable protective equipment.
- Do not reach into the open mechanism or the movement area of the product.



### **⚠ WARNING**

#### **Risk of injury from objects falling and being ejected!**

Falling and ejected objects during operation can lead to serious injury or death.

- Take appropriate protective measures to secure the danger zone.



### **⚠ WARNING**

#### **Risk of injury from objects falling during energy supply failure**

Products with a mechanical gripping force maintenance can, during energy supply failure, still move independently in the direction specified by the mechanical gripping force maintenance.

- Secure the end positions of the product with SCHUNK SDV-P pressure maintenance valves.



### **⚠ WARNING**

#### **Risk of injury due to unexpected movements!**

If the power supply is switched on or residual energy remains in the system, components can move unexpectedly and cause serious injuries.

- Before starting any work on the product: Switch off the power supply and secure against restarting.
- Make sure, that no residual energy remains in the system.

### 3 Technical data

Size	08	10	16	20	25	40
Stroke per jaw [mm]	2	3	5	6	8	13
Weight [kg]	0.04	0.07	0.15	0.25	0.46	1.48
Recommended workpiece weight [kg]	0.13	0.29	0.6	1.2	1.9	4.2
Max. permissible finger length [mm]	20	25	32	40	50	64
Max. permitted weight per finger [kg]	0.025	0.04	0.06	0.09	0.12	0.3
Ambient temperature [°C] Min. Max.	+5 +60					
Spring force gripping force maintenance [N] Min. Max.	3 6	8 13	10 25	20 50	40 80	125 125
Closing force [N] without gripping force maintenance with gripping force maintenance AS with gripping force maintenance IS	26 32 -	58 74 -	120 140 -	240 280 -	380 460 -	840 1090 -
Opening force [N] without gripping force maintenance with gripping force maintenance AS with gripping force maintenance IS	36 - 42	70 - 86	138 - 158	280 - 320	438 - 518	928 - 1178
IP rating	40					
Pressure medium	Compressed air, compressed air quality according to ISO 8573-1:7 4 4					
Min. pressure [bar] without gripping force maintenance with gripping force maintenance	2 4.5					
Max. pressure [bar] without gripping force maintenance with gripping force maintenance	8 6.5					

More technical data is included in the catalog data sheet.  
Whichever is the latest version.

## 4 Assembly

### 4.1 Mechanical connection



#### **⚠ WARNING**

##### **Risk of injury due to unexpected movements!**

If the power supply is switched on or residual energy remains in the system, components can move unexpectedly and cause serious injuries.

- Before starting any work on the product: Switch off the power supply and secure against restarting.
- Make sure, that no residual energy remains in the system.

#### **Evenness of the mounting surface**

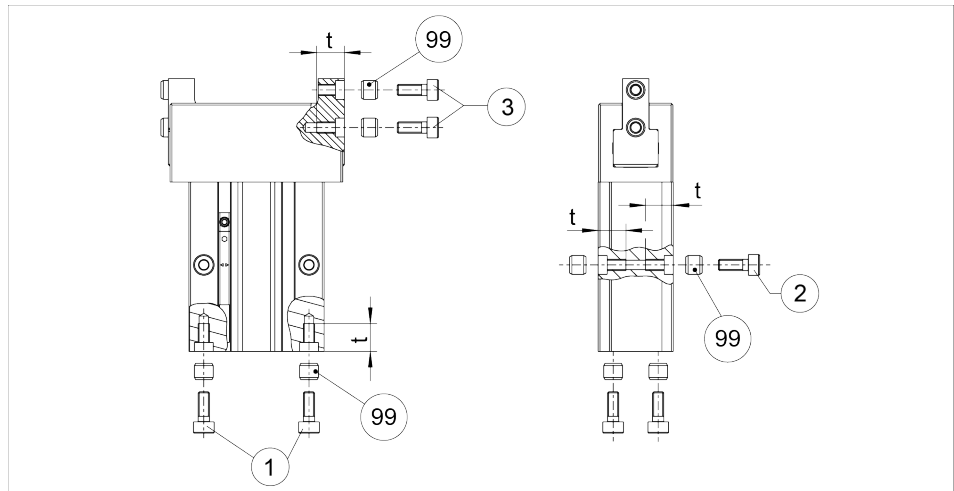
The values apply to the whole mounting surface to which the product is mounted.

*Requirements for evenness of the mounting surface (Dimensions in mm)*

Edge length	Permissible unevenness
< 100	< 0.02
> 100	< 0.05

**Mounting**

The module can be mounted from the rear or on the side.



*Assembly options*

Maximal screw-in depth of the fastening screws provided by the customer.

**Mounting material**

Item	Mounting	08	10	16	20	25	40
1	Module rear mounting		M3 / 6.5 deep		M4 / 8.5 deep	M5 / 11.5 deep	M8 / 15 deep
2	Module side mounting	M3	M3 / 6.5 deep		M4 / 8.5 deep	M5 / 11.5 deep	M8 / 16 deep
3	Top jaws		M3 / 6.5 deep		M4 / 8.5 deep	M5 / 11.5 deep	M8 / 16 deep
99	Centering sleeve	Ø2M6	Ø5K6		Ø7K6	Ø7K6	Ø12K6

**NOTE**

- Mount the module using the provided centering sleeves (99).
- Mount the module using the mounting bores.
- Mount the top jaws using the provided mounting bores .



## 4.2 Air connection

### **NOTICE**

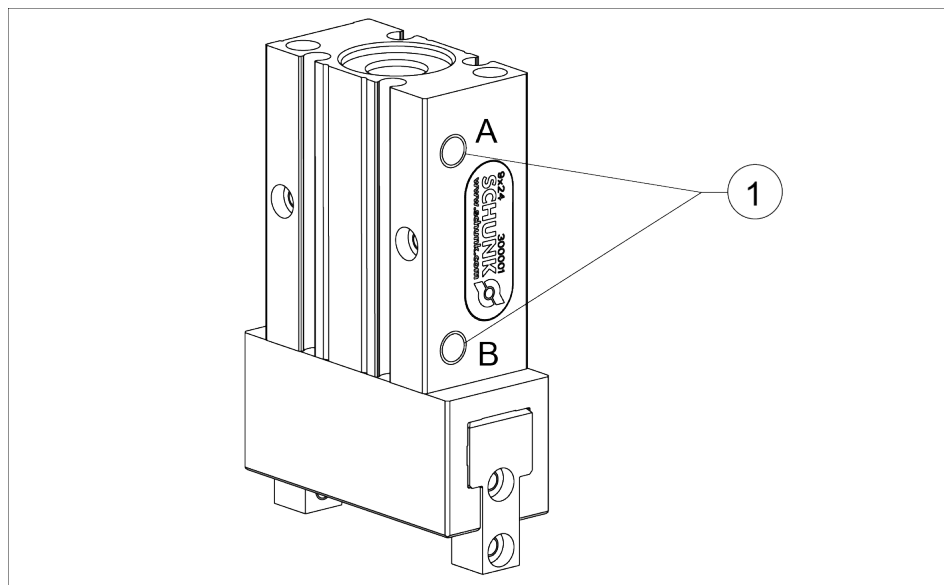
#### **Damage to the gripper is possible!**

If the maximum permissible finger weight or the permissible mass moment of inertia of the fingers is exceeded, the gripper can be damaged.

- A jaw movement always has to be without jerks and bounce.
- You must therefore implement sufficient reduction and/or damping.
- Observe the diagrams and information in the catalog data sheet.

### **NOTE**

- Observe the requirements for the compressed air supply, [Technical data](#) [▶ 14].
- In case of compressed air loss (cutting off the energy line), the components lose their dynamic effects and do not remain in a secure position. However, the use of a SDV-P pressure maintenance valve is recommended in this case in order to maintain the dynamic effect for some time. Product variants are also offered with mechanical gripping force via springs, which also ensure a minimum clamping force in the event of a pressure drop.



*Air connections*

**Thread diameter of the air connections**

Item	Connection	08	10	16	20	25	40
1	Thread diameter of the air connections (A = open, B = close)	2 x M3		2 x M5			2 x G1/8"

- Open only the air connections that are needed.
- Close unused main air connections using the screw plugs from the enclosed pack.
- For a hose-free direction connection, use the O-rings from the enclosed pack.

### 4.3 Sensors

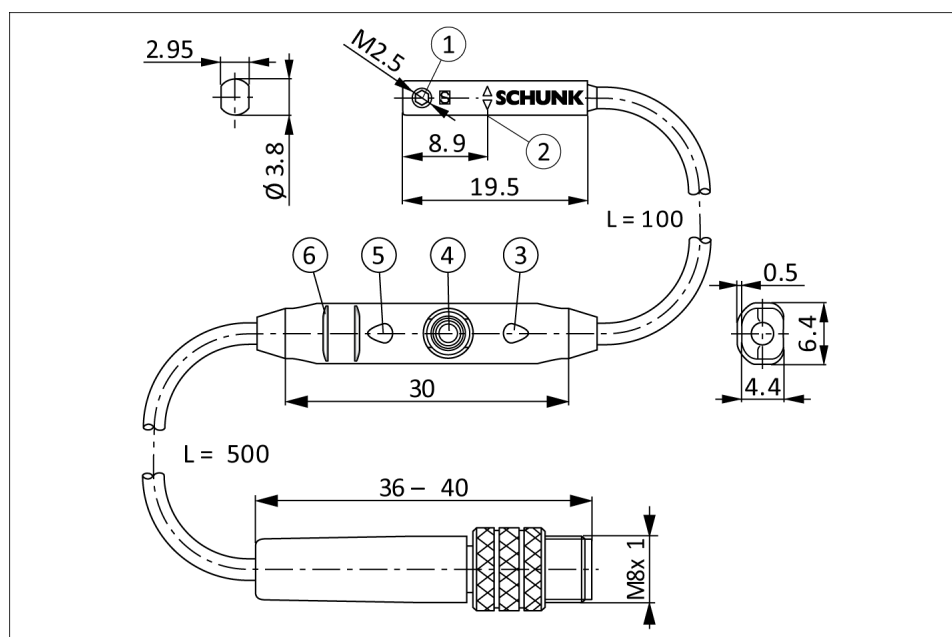
The gripper is prepared for use of the following sensors:

- Sensor MMS-P:
  - Information on handling sensors is available at [schunk.com](http://schunk.com) or from SCHUNK contact persons
  - Technical data for the sensors can be found in the data sheets (included in the scope of delivery or at [schunk.com](http://schunk.com)).
- Sensor ST4/ST4-2P
  - You can find information about the handling of sensors via the Aventics company
  - Technical data of the sensors are contained in the data sheets.

#### 4.3.1 Programmable magnetic switch (MMS-P)

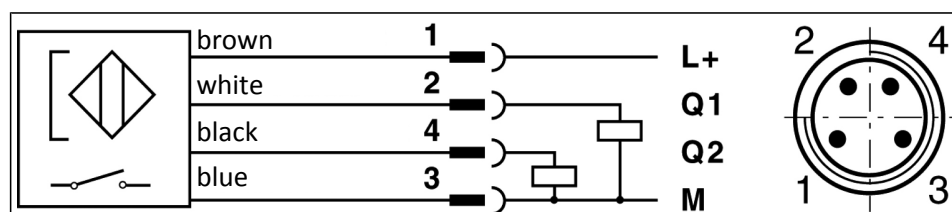
##### NOTE

The MMS-P can be used only for sizes GSP-P 08 – GSP-P 40.



Magnetic switch MMS-P 22

1	Mounting screw	4	Teach-button
2	Center sensor elements	5	LED display
3	LED display	6	Ribs for cable tires



Connection diagram PNP-4 conductor (MMS-P 22)

Types available for order (see catalog):

- MMS-P 22-S-M8-PNP
- MMSK-P 22-S-PNP
- V2-M8-4-2XM8-3

The MMSK-P 22-S-PNP features a cable with open strands so that it can be connected via terminal contacts.

The V2-M8-4-2XM8-3 distributor is used to convert the 4-pin connector plug of the MMS-P 22-S-M8-PNP sensor to two standard M8 plugs with 3 pins each.

## Mounting of the sensor

### NOTICE

**Sensor can be damaged during assembly.**

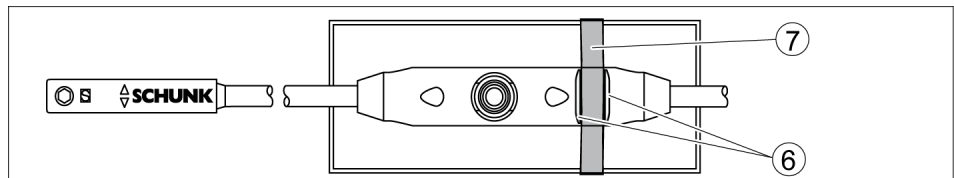
- Do not exceed the maximum tightening torque of 10 Ncm for the set screws!

### NOTE

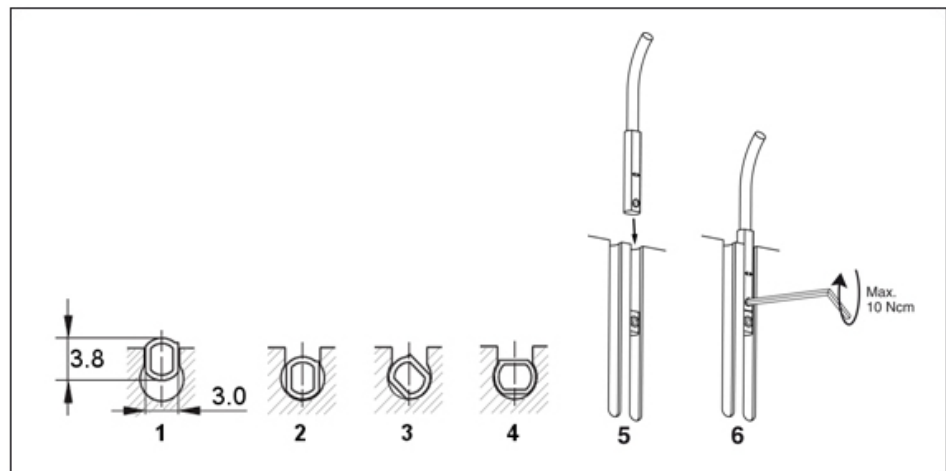
Ferromagnetic material changes the switching positions of the sensor (e.g. Adapter plate made of ordinary steel).

For ferromagnetic adapter plates:

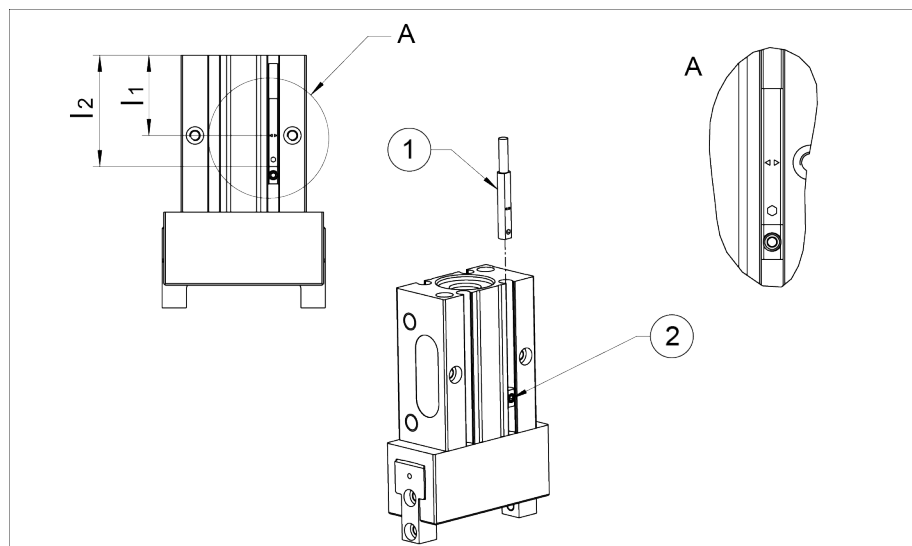
- The module must be first mounted on the adapter plate.
- Then, the position of the magnetic switches has to be set.



- To relieve the cable, the electronics have to be fixed in place using cable ties (7). There are ribs (6) in place on the electronics for mounting purposes.



- Turn in the sensor (1 - 4).  
OR  
Push the sensor axially into the slot until it contacts the stop (5).
- Fix the sensor with an Allen wrench (6).



If there is no terminal stop, then slide the magnetic switch according to dimension  $l_2$  (bottom edge of gripper up to front side of sensor) or according to dimension  $l_1$  (bottom edge of gripper up to double arrow on sensor) and then clamp it with an Allen wrench.

Type	Dimension I <sub>1</sub> [mm]	Dimension I <sub>2</sub> [mm]	Type	Dimension I <sub>1</sub> [mm]	Dimension I <sub>2</sub> [mm]
GSP-P 08	19.2	28.1	GSP-P 20-AS	22.1	31
GSP-P 08-AS	14.1	23.0	GSP-P 20-IS	27.1	36
GSP-P 08-IS	22.4	31.3	GSP-P 25	33.6	42.5
GSP-P 10	20.4	29.3	GSP-P 25-AS	25.6	34.5
GSP-P 10-AS	17.9	26.8	GSP-P 25-IS	33.6	42.5
GSP-P 10-IS	20.4	29.3	GSP-P 40	47.8	56.7
GSP-P 16	25.0	33.9	GSP-P 40-AS	31.8	40.7
GSP-P 16-AS	21.0	29.9	GSP-P 40-IS	47.8	56.7
GSP-P 16-IS	25.0	33.9			
GSP-P 20	27.1	36			

**Setting up  
the switching points**

- Keep the Teach-Button (4) pressed for 2 seconds.
  - ✓ After 2 seconds LED 1 (3) is flashing.
- Move the gripper into position 1 (e.g. "open").
- Press the Teach-Button (4) briefly.
  - ✓ LED 1 (3) lights up and LED 2 (5) is flashing.
- Move the gripper manually into position 2 (z.B. „-2mm“).
  - ✓ LED 1 (3) should turn off as soon as the switching point 1 is left.
- The switching points are set.
  - ✓ LED 2 (5) lights up.
- ✓ The switching points are set.

## Adjusting the hysteresis

The hysteresis to both switching points will be adjusted automatically corresponding to the characteristics of the magnetic field.

The user can set the switching and triggering points of each position a little bit closer than for the automatic mode. The triggering point is closer to the switching point. At the same time the susceptibility to trouble and damage increases. In the mode of the lowest hysteresis, an error signal (such as jitter or untimely switch off) can be avoided, if the sensor is protected against all types of disturbances (i.e. by shielding). Frequent types of disturbances are change in temperature and electro-magnetic influences.

Within the closest fine-teach mode, SCHUNK cannot guarantee EMC-compatibility any more.

The hysteresis adjustment is used for the manual adjustment of the switching points (if necessary).

In case that the hysteresis automatically determined by the sensor should be too high or too low after “the adjustment of the switching points”, you may correct the value as follows.

The sensor avoids a too small hysteresis during hysteresis adjustment.

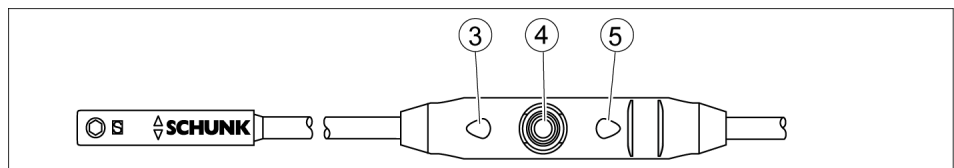
### Sensors MMS 22, MMS-P 22, MMS 22-PI1 and MMS 22-PI2

The smallest detectable difference in stroke is defined in the following table:

*The smallest detectable difference in stroke based on the nominal stroke*

For grippers with X mm nominal stroke per jaw	Min. query range per jaw/ min. queried stroke difference per jaw
$X \leq 5 \text{ mm}$	30% of the nominal stroke per jaw
$X > 5 \text{ mm to } X \leq 10 \text{ mm}$	20% of the nominal stroke per jaw
$X > 10 \text{ mm}$	10% of the nominal stroke per jaw

**Example:** Product with 7 mm nominal stroke per jaw  
 $7 \text{ mm} * 20\% = 1.4 \text{ mm}$



- Press the Teach-Button (4) for 5 seconds.
  - ✓ LED 1 (3) flashes from the 2nd to the 5th second.
  - ✓ LED 1 will stop flashing once the 5 seconds are over.
- Teach-Knopf loslassen.
- Put the gripper to position „switch-off point of switching point 1“.
- Press the Teach-Button (4) briefly. LED 1(3) will flash twice.
- Put the gripper to position „switch-off point of switching point 2“.
- Press the Teach-Button (4) briefly.
  - ✓ LED 2 (5) will flash twice.
- ✓ The mounting of the sensor MMS-P is completed.



### 4.3.2 Proximity switch ST4 and ST4-2P

The proximity switch ST4 or ST4-2 P by Aventics can be mounted on the gripper. The proximity switches have to be ordered directly from Aventics.

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#### **NOTE**

For mounting using through bolts, V2A stainless steel bolts must be used instead of ferromagnetic bolts.

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Fix the proximity switch ST4 or ST4-2P with the provided centering rings in the intended position, see documentation of the sensors.

## 5 Troubleshooting

### 5.1 Product does not move

Possible cause	Corrective action
Base jaws jam in housing, e.g. mounting surface is not sufficiently even.	Check the evenness of the mounting surface. <a href="#">Mechanical connection</a> [▶ 15] Loosen the mounting screws of the product and actuate the product again.
Pressure drops below minimum.	Check air supply. <a href="#">Air connection</a> [▶ 17]
Compressed air lines switched.	Check compressed air lines.
Proximity switch defective or set incorrect.	Readjust or change sensor.
Unused air connections open.	Close unused air connections.
Flow control valve closed.	Open the flow control valve.
Component part defective.	Exchange product
The aperture angle is limited to 0°.	Check opening angle limitation.

### 5.2 Product does not travel through the entire stroke

Possible cause	Corrective action
Pressure drops below minimum.	Check air supply. <a href="#">Air connection</a> [▶ 17]
Mounting surface is not sufficiently flat.	Check the evenness of the mounting surface. <a href="#">Mechanical connection</a> [▶ 15]
Component part defective.	Exchange product

### 5.3 Product opens or closes abruptly

Possible cause	Corrective action
Compressed air lines blocked.	Check compressed air lines of damage.
Mounting surface is not sufficiently flat.	Check the evenness of the mounting surface.
One-way flow control valve is missing or adjustet incorrectly.	Install and adjust one-way flow control valve.
Loading too large.	Check permissible weight and length of the gripper fingers. <a href="#">Mechanical connection</a> [▶ 15]

### 5.4 Magnetic switch does not work

Possible cause	Corrective action
Steel screws were used to mount the gripper	Use VA-screws
Mounting plates, brackets, etc. from non-magnetic materials	If possible, use aluminium or plastic

### 5.5 Gripping force drops

Possible cause	Corrective action
Compressed air can escape.	Check seals, if necessary replace product.
Pressure drops below minimum.	Check air supply. <a href="#">Air connection</a> [▶ 17]

### 5.6 Product does not achieve the opening and closing times

Possible cause	Corrective action
Compressed air lines are not installed optimally.	<p>If present: Open the flow control couplings on the product to the maximum that the movement of the jaws occurs without bouncing and hitting.</p> <p><b>NOTICE! The one way flow control valves must not be removed even when the product has reached the opening and closing times.</b></p> <p>Check compressed air lines.</p> <p>Inner diameters of compressed air lines are of sufficient size in relation to compressed air consumption.</p> <p>Keep compressed air lines between the product and directional control valve as short as possible.</p> <p>Flow rate of valve is sufficiently large relative to the compressed air consumption.</p>
Loading too large.	Check permissible weight and length of the gripper fingers.

## **6 Maintenance and Care**

The product is not intended for maintenance.

Disassembly for maintenance or repair purposes is not possible.

A damaged product has to be replaced completely.

## 7 Translation of original declaration of incorporation

in terms of the Directive 2006/42/EG, Annex II, Part 1.B of the European Parliament and of the Council on machinery.

Manufacturer/  
Distributor

SCHUNK GmbH & Co. KG Spann- und Greiftechnik  
Bahnhofstr. 106 – 134  
D-74348 Lauffen/Neckar

We hereby declare that on the date of the declaration the following partly completed machine complied with all basic safety and health regulations found in the directive 2006/42/EC of the European Parliament and of the Council on machinery. The declaration is rendered invalid if modifications are made to the product.

Product designation: 2-Finger-parallel gripper / GSP-P / pneumatic  
ID number 311010, 311011, 311012, 311020, 311021, 311022,  
311030, 311031, 311032, 311050, 311051, 311052, 311060,  
311061, 311062, 311080, 311081, 311082, 30040466

The partly completed machine may not be put into operation until conformity of the machine into which the partly completed machine is to be installed with the provisions of the Machinery Directive (2006/42/EC) is confirmed.

Applied harmonized standards, especially:

EN ISO 12100:2010 Safety of machinery - General principles for design -  
Risk assessment and risk reduction

The manufacturer agrees to forward on demand the relevant technical documentation for the partly completed machinery in electronic form to national authorities.

The relevant technical documentation according to Annex VII, Part B, belonging to the partly completed machinery, has been created.

Person authorized to compile the technical documentation:  
Robert Leuthner, Address: see manufacturer's address

*Signature: see original declaration*

Lauffen/Neckar, June 2019

p.p. Ralf Winkler,  
Manager for development  
of gripping system components

## 7.1 Annex to Declaration of Incorporation

according 2006/42/EG, Annex II, No. 1 B

1. Description of the essential health and safety requirements pursuant to 2006/42/EC, Annex I that are applicable and that have been fulfilled with:

Product designation	2-Finger-parallel gripper
Type designation	GSP-P
ID number	311010, 311011, 311012, 311020, 311021, 311022, 311030, 311031, 311032, 311050, 311051, 311052, 311060, 311061, 311062, 311080, 311081, 311082, 30040466

To be provided by the System Integrator for the overall machine	↓
Fulfilled for the scope of the partly completed machine	↓
Not relevant	↓

1.1	Essential Requirements			
1.1.1	Definitions		X	
1.1.2	Principles of safety integration		X	
1.1.3	Materials and products		X	
1.1.4	Lighting		X	
1.1.5	Design of machinery to facilitate its handling		X	
1.1.6	Ergonomics		X	
1.1.7	Operating positions			X
1.1.8	Seating			X

1.2	Control Systems			
1.2.1	Safety and reliability of control systems		X	
1.2.2	Control devices		X	
1.2.3	Starting		X	
1.2.4	Stopping		X	
1.2.4.1	Normal stop		X	
1.2.4.2	Operational stop		X	
1.2.4.3	Emergency stop		X	
1.2.4.4	Assembly of machinery		X	
1.2.5	Selection of control or operating modes		X	
1.2.6	Failure of the power supply			X

1.3	Protection against mechanical hazards			
1.3.1	Risk of loss of stability			X
1.3.2	Risk of break-up during operation			X
1.3.3	Risks due to falling or ejected objects			X
1.3.4	Risks due to surfaces, edges or angles		X	

<b>1.3</b>	<b>Protection against mechanical hazards</b>			
1.3.5	Risks related to combined machinery			X
1.3.6	Risks related to variations in operating conditions			X
1.3.7	Risks related to moving parts		X	
1.3.8	Choice of protection against risks arising from moving parts			X
1.3.8.1	Moving transmission parts		X	
1.3.8.2	Moving parts involved in the process			X
1.3.9	Risks of uncontrolled movements			X
<b>1.4</b>	<b>Required characteristics of guards and protective devices</b>			
1.4.1	General requirements			X
1.4.2	Special requirements for guards			X
1.4.2.1	Fixed guards			X
1.4.2.2	Interlocking movable guards			X
1.4.2.3	Adjustable guards restricting access			X
1.4.3	Special requirements for protective devices			X
<b>1.5</b>	<b>Risks due to other hazards</b>			
1.5.1	Electricity supply		X	
1.5.2	Static electricity		X	
1.5.3	Energy supply other than electricity		X	
1.5.4	Errors of fitting		X	
1.5.5	Extreme temperatures			X
1.5.6	Fire			X
1.5.7	Explosion			X
1.5.8	Noise			X
1.5.9	Vibrations			X
1.5.10	Radiation	X		
1.5.11	External radiation	X		
1.5.12	Laser radiation	X		
1.5.13	Emissions of hazardous materials and substances			X
1.5.14	Risk of being trapped in a machine	X		
1.5.15	Risk of slipping, tripping or falling	X		
1.5.16	Lightning			X
<b>1.6</b>	<b>Maintenance</b>			
1.6.1	Machinery maintenance		X	
1.6.2	Access to operating positions and servicing points		X	
1.6.3	Isolation of energy sources		X	
1.6.4	Operator intervention		X	
1.6.5	Cleaning of internal parts		X	

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<b>1.7</b>	<b>Information</b>			
1.7.1	Information and warnings on the machinery		X	
1.7.1.1	Information and information devices		X	
1.7.1.2	Warning devices		X	
1.7.2	Warning of residual risks		X	
1.7.3	Marking of machinery	X		
1.7.4	Instructions	X		
1.7.4.1	General principles for the drafting of instructions	X		
1.7.4.2	Contents of the instructions	X		
1.7.4.3	Sales literature	X		
	<b>The classification from Annex 1 is to be supplemented from here forward.</b>			
2	Supplementary essential health and safety requirements for certain categories of machinery			X
2.1	Foodstuffs machinery and machinery for cosmetics or pharmaceutical products			X
2.2	Portable hand-held and/or guided machinery			X
2.2.1	Portable fixing and other impact machinery			X
2.3	Machinery for working wood and material with similar physical characteristics			X
3	Supplementary essential health and safety requirements to offset hazards due to the mobility of machinery		X	
4	Supplementary essential health and safety requirements to offset hazards due to lifting operations		X	
5	Supplementary essential health and safety requirements for machinery intended for underground work			X
6	Supplementary essential health and safety requirements for machinery presenting particular hazards due to the lifting of persons		X	